Introduction Arduino Portable

This document explains how to install a portable version of the Arduino Software (IDE). This portable version contains all the files and directories necessary to work with the Bionic Flower. Thus, it allows you to start right away with programming the Bionic Flower without any extra library downloads/installations or delays.

Download

Go to the stem.festo website and download the compressed (.zip) file.

https://stem.festo.com/us/en/products-courses/coding/open-roberta-lab/index.html

Tutorial – Program your Bionic Flower with the Open Roberta Lab

In this video you will learn how to use Open Roberta Lab in connection with the Bionic Flower. You will learn how to use the Open Roberta Connecter, which allows you to receive codes from multiple devices like tablets and transfer them to the Bionic Flower. This also makes it possible to use the robot flower in the classroom. Have fun coding!

Advanced coding activities with the Bionic Flower

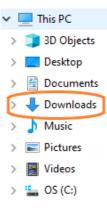
You can also program our Bionic Flower yourself. Therefore, you don't need any long installation. You can download the Arduino Portable version with all necessary and pre-installed settings. We also have prepared some basic DIY-project ideas for an easy start with coding our Bionic Flower.

Arduino Portable version (zip)

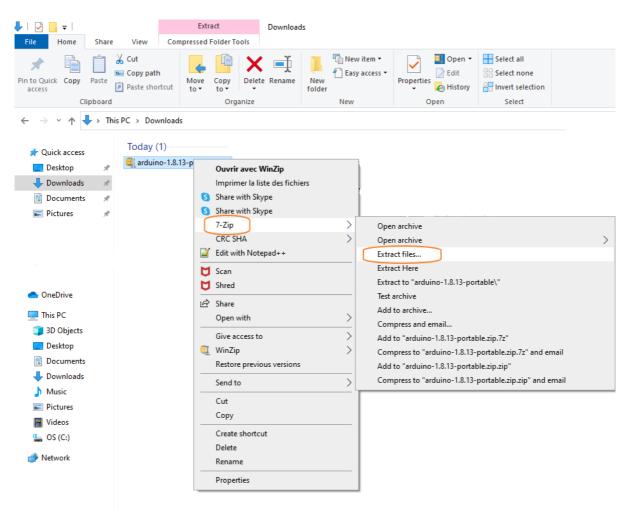
- Introduction (pdf)
- Instructions can also be found on Github

Unzip

Once the download is completed, you will find the file in zip format in the download folder of your computer.



You need to unzip it to access the file, for that right click on the mouse on the computer and select "7-Zip" -> "Extract files...".



Now a window opens, you must now select the location of the file in your documents. For that you can create a folder named like this: *Name_Bionic_Flower_Project*

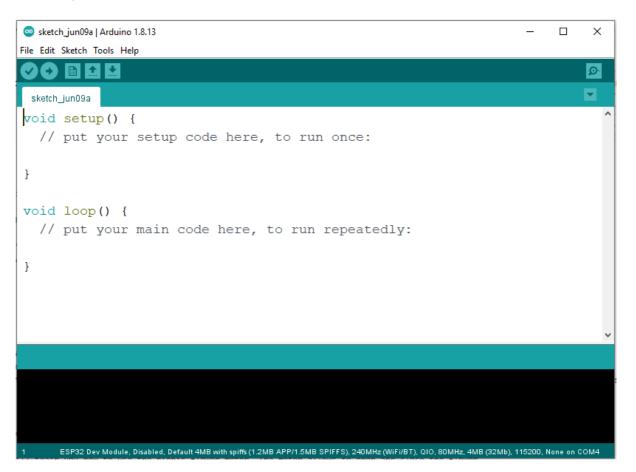
Extract : C:\Users\verni\Downloads\arduino-1.8.13-portable.zip ×				
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Path mode: Full pathnames ~ Eliminate duplication of root folder	Show Password			
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ОК	Cancel Help			

Start with Arduino IDE

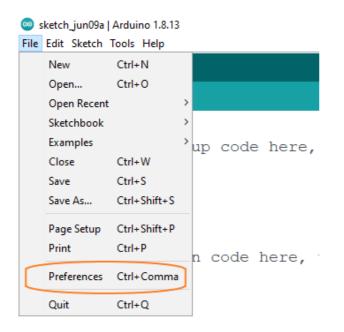
Now that everything is installed, you need to run the Arduino software.

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	revisions.txt			ocument 94	
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A window opens, this is the user interface of the Arduino IDE.



To access all the functionality of the Arduino portable version you have to change the directory. For that, click on *File -> Preferences*.



Once opened the preferences window you have to select the directory of your file Name_Bionic_Flower_Project.

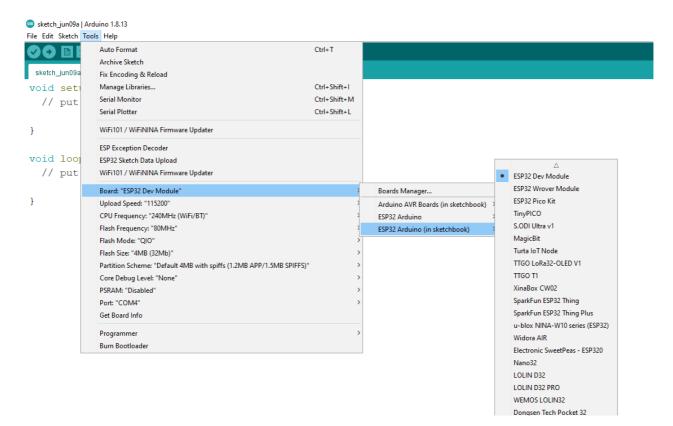
Preferences		×		
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C: \Users\verni\Documents\Festo\Bionic flower\Arduino_portable\arduino-1.8.13	3-portable\arduino-1.8.13	Browse		
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Verify code after upload	Use external editor			
Check for updates on startup	Save when verifying or uploading			
Use accessibility features				
Additional Boards Manager URLs: https://dl.espressif.com/dl/package_esp32_index.json				
More preferences can be edited directly in the file				
C:\Users\verni\AppData\Local\Arduino15\preferences.txt				
(edit only when Arduino is not running)				
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ESP32 module connection

You have to connect the ESP32 module to your computer via a USB port. If your computer doesn't find the ESp32 module you have to install the driver manually. Therefore go to SiliconLabs, navigate to *Downloads* and download *CP210x Universal Windows Driver*. After that, you have to make sure that you selected the right port. For that selecte *Tools -> Port*.

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	Archive Sketch		
sketch_jun09a	Fix Encoding & Reload		
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// put	Serial Monitor	Ctrl+Shift+M	
	Serial Plotter	Ctrl+Shift+L	
}	WiFi101 / WiFiNINA Firmware Updater		
	ESP Exception Decoder		
void loop	ESP32 Sketch Data Upload		
// put	WiFi101 / WiFiNINA Firmware Updater		
	Board: "ESP32 Dev Module"	>	
}	Upload Speed: "115200"	>	
	CPU Frequency: "240MHz (WiFi/BT)"	>	
	Flash Frequency: "80MHz"	>	
	Flash Mode: "QIO"	>	
	Flash Size: "4MB (32Mb)"	>	
	Partition Scheme: "Default 4MB with spiffs (1.2MB APP/1.5MB SPIFFS)"	>	
	Core Debug Level: "None"	>	
	PSRAM: "Disabled"	>	
	Port: "COM4"	;	Serial ports
	Get Board Info		COM4
	Programmer	>	
	Burn Bootloader		
			-

Make sure that the type of micropocessor is the ES32 module. For this select Tools.

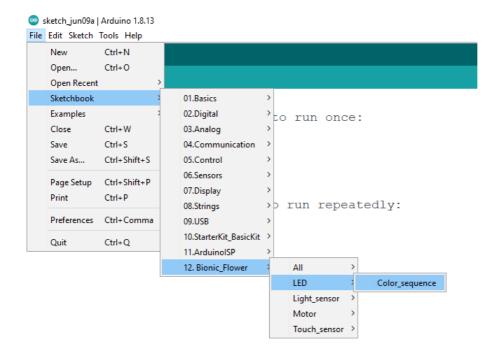


Now, you are ready to start your first code with the Bionic Flower !

First test with the Bionic Flower

Some code have been created specifically for you to learn about the Bionic Flower. You can find them by selecting *File -> Sketchbook -> 12.Bionic_Flower*.

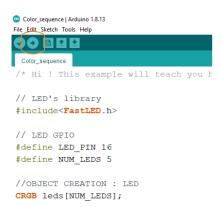
Let's start with the code to work with led LED : color_sequence.ino.



A new window opens with the code for the LED.



After reading the code, you can implement the code, i.e. downloaded the code on the ESP32 module. For this you click on right arrow button.



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If everything went well the Bionic Flower changes color !

You can use the same procedure to work with the other sample code of the Bionic Flower.

• LEDs

-> Color_sequence.ino : This example teach you how to change the color of the LEDs and create a color sequence (red,blue,green).

• Motor

-> Motor_Open_Close.ino : This example will teach you how to use the Bionic Flower motor. The motor allows to open and close the flower.

• Touch sensor

-> Right_Left.ino : This example will teach you how to use the touche sensor and display a message if a touch is detected.

-> Open_close_flower.ino : This example will teach you how to use the touch sensor to open or close the flower. For this you need to know how use the motor and the touch sensor.

-> Change_color.ino : This example will teach you how to use the touch sennsor to change the color of the flower. For this you need to know how use the LEDs and the touch sensor.

• Light sensor

-> Light_value.ino : This example will teach you how to use the light sensor and display the luminosity value on the serial monitor.

-> Day_Night_Color.ino : This example will teach you how to use light sensor to change the flower's color. If it is the day, the flower lights yellow. If it is the night, the flower lights blue.

• All components

-> Light_Touch_LED_Motor.ino: This example will teach you how to use 2 sensors with the I2C communication. If a right touch is detected the flower is opening. If a left touch is detected the flower is closing. In addition, if the luminosity is enough the flower is yellow, otherwise the flower is yellow.