## **Bionics4Education**



Tasks are identified in no particular order. Use this information to complete the project management document.

Insert batteries in battery compartment	Make intermediate plates	Connect connecting piece with 3- arm bracket	Evaluate project result
Draw the sealing rings on the connecting piece	Locate material (painting rolls, cardboard)	Connect the waterproof servo motor to the connecting piece	Optimize the gripping process
Mount servo motor on 3-arm bracket	Thread the intermediate plates and painting rollers alternately	Connect 3-armed bracket with trunk	Documentation (Film)
Connect the body to the connecting piece	Place the battery compartment in the body	Connect the battery connection cable to the battery compartment	Prepare work area
Cut paint rollers to size	Connect FinRays with FinRay holder (gripper)	Optional: Advanced activities	Check completeness of the kit
Connect servo motors with electronics board	Connect the electronic board to the battery compartment	Guide the servo motor plug cable through eyelets in 3-arm bracket	Clean up your work area
Lead the blue silicone tube through the middle hole	Connect the device to the microcontroller's WLAN	Connect cable ties with three outer rudder horns	Lead cable ties through middle silicone tubing and gripper FinRay
Control steering / Testing	Locate objects to grasp	Guide three cable ties through FinRay holder	Disassemble the robot
Connect the middle cable tie to the rudder horn of the waterproof servo motor	Print / Present project plan	Monitor project progress	Monitor task times to ensure timeline on target
Create and add design elements	Analyze biological role model	Evaluate team work	Slide the electronics board into the body guide rail